



FZI Forschungszentrum Informatik



Contract Automata

A Specification Language for Mode-Based Systems

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State of the Art

Design-By-Contract

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- Useful for single operation, difficult for *reactive system*
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Contract Automata: Contract-based specification with FSM

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Focus of this presentation

Specification mechanism, Concept, High-Level

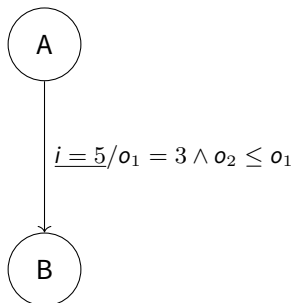
- Like nondet. FSM but every edge has *assumption/guarantee*
- Mode may represent internal system or environment state



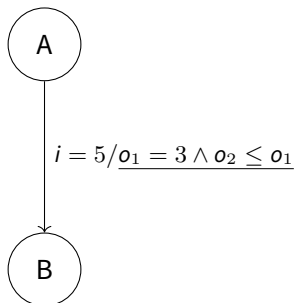
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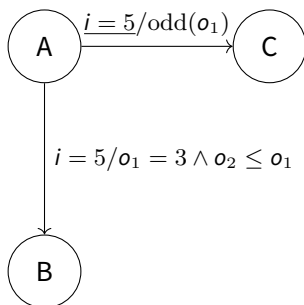
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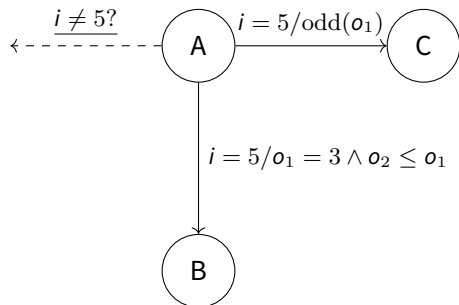
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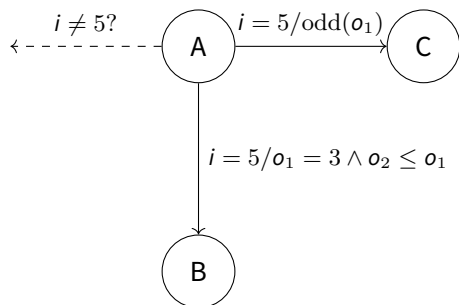


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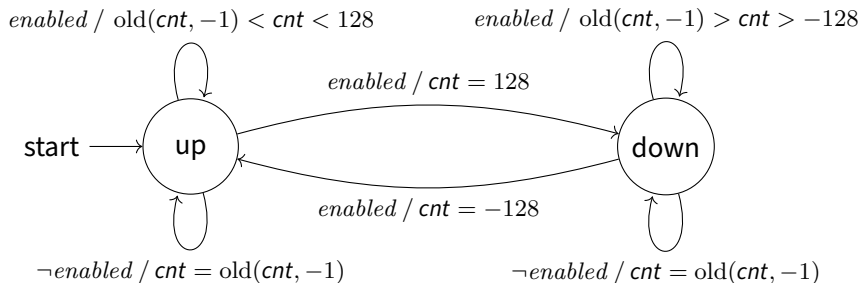


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if no assumption holds

- Like nondet. FSM but every edge has *assumption/guarantee*
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- “Uncovered” (i.e. valid): if no assumption holds
- Violation: if any assumption but no guarantee holds



Response Function

$$R : \mathcal{I}^* \rightarrow \mathcal{O}$$

- Map inputs *up to now* to next output

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$$R : \mathcal{I}^* \rightarrow \mathcal{O}$$

System Behaviour

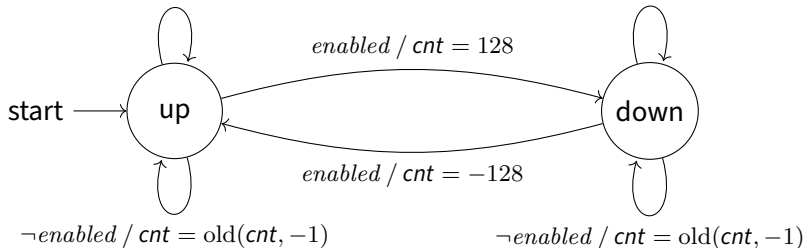
$$\mathcal{B}(R) = \{((i_0, o_0), (i_1, o_1), \dots) \mid R(i_0, \dots, i_n) = o_n, n \in \mathbb{N}\}$$

- Map inputs *up to now* to next output
- Behaviour is set of infinite I/O-traces

Possible Behavior of Counter

$enabled / old(cnt, -1) < cnt < 128$

$enabled / old(cnt, -1) > cnt > -128$



Traces

$\mathcal{B}(R) = \{((t, 1), (f, 1), (t, 2), \dots), ((t, 1), (t, 2), (t, 3), \dots), \dots\}$

but also

$\mathcal{B}(R) = \{((t, 5), (t, 42), \dots), \dots\}$,

$\mathcal{B}(R) = \{((t, 64), (t, 128), (t, 64), (t, 32), \dots), \dots\}$

Intuitively

- At every step: “Inputs satisfy assumptions \rightarrow Output must satisfy guarantee”
- Systems takes path through CA that satisfies contracts on each edge

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Caveats

- Mode not explicit in system
- Bridge gap between syntactic “contract paths” and semantic I/O-traces

Game Semantics (simplified)

Input: Reactive Systeme $R : \mathcal{I}^* \rightarrow \mathcal{O}$ and CA

$\hat{S} \leftarrow S_0; \quad \bar{\sigma} \leftarrow \varepsilon; \quad \bar{I} \leftarrow \varepsilon;$

while true do

Environment chooses input $i \in \mathcal{I};$

$\bar{I} \leftarrow \bar{I} \cdot i;$

System computes response $o = R(\bar{I}) \in \mathcal{O};$

$\bar{\sigma} \leftarrow \bar{\sigma} \cdot (i, o);$

$\hat{E} \leftarrow \{(s, c, s') \in \delta \mid \bar{\sigma} \models \text{assume}(c)\};$

if $\hat{E} = \emptyset$ then

return *System wins*;

end

$\hat{S} \leftarrow \{s' \mid (s, c, s') \in \hat{E} \wedge \bar{\sigma} \models \text{guarantee}(c)\};$

if $\hat{S} = \emptyset$ then

return *Environment wins*;

end

end

Additional Concepts

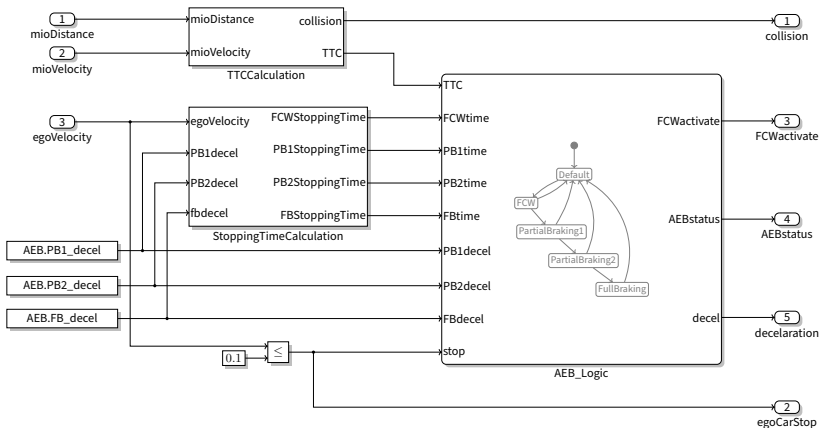
$A \preceq B$

- Based on LSP: $c^A \preceq c^B$ iff.
assume(c^B) \rightarrow assume(c^A) and
guarantee(c^A) \rightarrow guarantee(c^B)
- All contracts along path must be refinements
- Every path in A is refinement of path in B

- Sequential execution: $C := A \xrightarrow{oi} B$
- *oi* defines *output* to *input* mapping

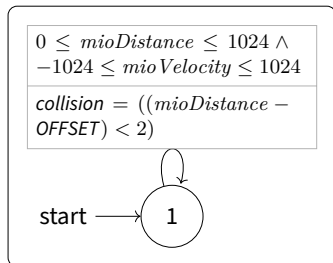
- Sequential execution: $C := A \xrightarrow{oi} B$
- oi defines *output* to *input* mapping
- Parallel execution: $A \parallel B := A \xrightarrow{\emptyset} B$

Emergency Break Assistant

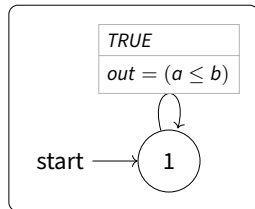


Formula

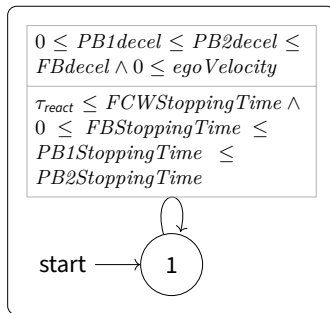
$$(TTCCalculation \parallel StoppingTimeCalculation \parallel \leq) \xrightarrow{oi} AEB_Logic \preceq AEB$$



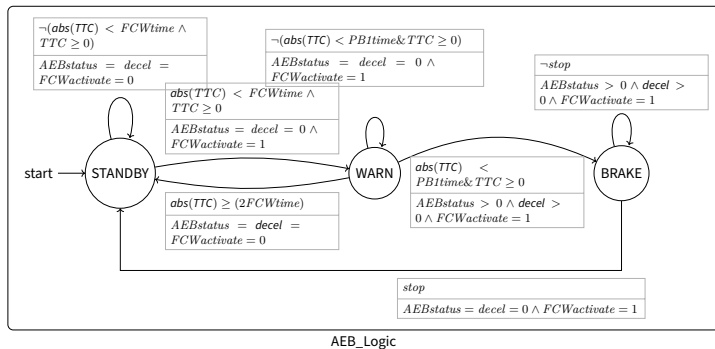
TTCalculation

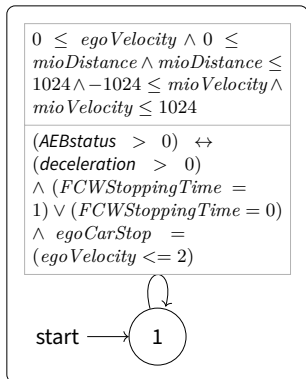


≤



StoppingTimeCalculation





AEB

Results

- If car is not standing still and the system is engaged, the car is decelerating
- Interesting behavior mostly in AEB_Logic

Contract Automata

- Mode-based reactive systems w/ Design-by-Contract
- Modular: Refinement & Composition
- Implementation and Case study available
- Submitted @ iFM'23

Future Work

- Specification Mining
- Runtime Verification
- Tooling (visualization, editing, etc.)

